

Contents

1 Hilbert Space	1
1.1 Definition	1
1.2 Projection theory	2
2 The Geometry of Influence Functions	3
2.1 Super-Efficiency	3
2.2 Geometry of Influence Functions for Parametric Models	4
2.3 Constructing Estimators	4

1 Hilbert Space

1.1 Definition

We will focus primarily on the Hilbert space whose elements are random vectors with mean zero and finite variance. For random variable Z , it is equipped with an underlying probability space $(\mathcal{Z}, \mathcal{A}, P)$, where \mathcal{Z} is the sample space, \mathcal{A} is the corresponding σ -algebra, and P is the probability measure. Consider the space consisting of q -dimensional mean-zero random functions of Z ,

$$h : \mathcal{Z} \rightarrow \mathbb{R}^q$$

where $h(Z)$ is measurable and also satisfies

- (i) $E\{h(Z)\} = 0$
- (ii) $E\{h^T(Z)h(Z)\} < \infty$

In the same way that we consider points in Euclidean space as vectors from the origin, here we will consider the q -dimensional random functions as points in a space. Therefore, we define the origin of this space as

$$h(Z) = 0^{q \times 1}$$

A Hilbert space, denoted by \mathcal{H} , is a complete normed *linear vector space* equipped with an *inner product*. As well as being a linear space, a Hilbert space also allows us to consider distance between elements and angles and orthogonality between vectors in the space. This is accomplished by defining an inner product.

Definition 1.1. (Inner product)

Corresponding to each pair of elements h_1, h_2 belonging to a linear vector space \mathcal{H} , an inner product, defined by $\langle h_1, h_2 \rangle$, is a function that maps to the real line. That is, $\langle h_1, h_2 \rangle$ is a scalar that satisfies

1. $\langle h_1, h_2 \rangle = \langle h_2, h_1 \rangle$
2. $\langle h_1 + h_2, h_3 \rangle = \langle h_1, h_3 \rangle + \langle h_2, h_3 \rangle$, with $h_1, h_2, h_3 \in \mathcal{H}$
3. $\langle \lambda h_1, h_2 \rangle = \lambda \langle h_1, h_2 \rangle$
4. $\langle h_1, h_1 \rangle \geq 0$ with equality if and only if $h_1 = 0$

Definition 1.2. (Inner product for q -dimensional measurable random functions)

$$\langle h_1, h_2 \rangle = E(h_1^T h_2)$$

Definitions that follows

1. *equivalence*: $h_1 \equiv h_2$ if $h_1 = h_2$ a.e.
2. *norm/length*: $\|h\| = \langle h, h \rangle^{1/2}$
3. *orthogonality*: $h_1 \perp h_2$ if $\langle h_1, h_2 \rangle = 0$

Definition 1.3. (linear subspace)

A space $\mathcal{U} \subset \mathcal{H}$ is a linear subspace if $u_1, u_2 \in \mathcal{U}$ implies $au_1 + bu_2 \in \mathcal{U}, \forall a, b \in \mathbb{R}$. A linear subspace must contain the origin. This is clear by letting the scalars be $a = b = 0$

Theorem 1.4. (Cauchy-Schwartz inequality)

$\forall h_1, h_2 \in \mathcal{H}$

$$|\langle h_1, h_2 \rangle|^2 \leq \|h_1\|^2 \|h_2\|^2$$

with equality holds if and only if $h_1 = ch_2$ for some $c \in \mathbb{R}$

1.2 Projection theory

Theorem 1.5. (projection of h onto \mathcal{U})

Let \mathcal{H} be a Hilbert space and \mathcal{U} a linear subspace that is closed (i.e., contains all its limit points). Corresponding to any $h \in \mathcal{H}$, there exists a unique $u_0 \in \mathcal{U}$ that is closest (in terms of the distance defined above) to h ; that is

$$\|h - u_0\| \leq \|h - u\|, \quad \forall u \in \mathcal{U},$$

in addition, $(h - u_0) \perp \mathcal{U}$, that is

$$\langle h - u_0, u \rangle = 0, \quad \forall u \in \mathcal{U}.$$

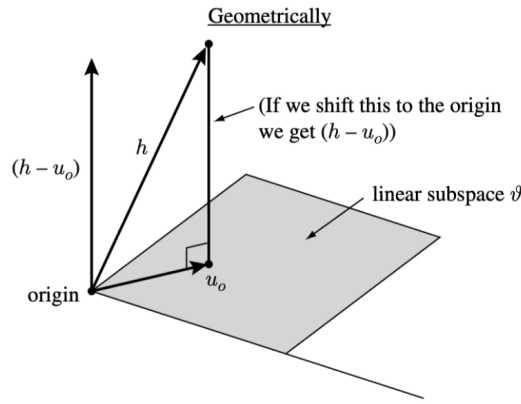


Figure 1: Projection onto a linear subspace

Theorem 1.6. (Pythagorean Theorem)

if $h_1, h_2 \in \mathcal{H}$ and $h_1 \perp h_2$ then

$$\|h_1 + h_2\|^2 = \|h_1\|^2 + \|h_2\|^2$$

Example 1. (One-Dimensional Random Functions)

Consider the Hilbert space \mathcal{H} of one-dimensional random functions, $h(Z)$, with mean zero and finite variance. Let $u_1(Z), \dots, u_k(Z) \in \mathcal{H}$, then \mathcal{U} is the linear subspace spanned by $\{u_1, \dots, u_k\}$.

$$\mathcal{U} = \{a^T u; \text{ for } a \in \mathbb{R}^k\}, \quad u^{k \times 1} = \begin{pmatrix} u_1 \\ \vdots \\ u_k \end{pmatrix}$$

u is the basis.

To derive the projection of $\forall h \in \mathcal{H}$, let's go through the following steps

$$\begin{aligned} \langle h - a_0^T u, a^T u \rangle &= 0, \quad \forall a = (a_1, \dots, a_k)^T \in \mathbb{R}^k \\ E(hu^T) - a_0^T E(uu^T) &= 0^{(1 \times k)} \\ a_0^T &= E(hu^T) \{E(uu^T)\}^{-1} \\ u_0 &= a_0^T u = E(hu^T) \{E(uu^T)\}^{-1} u. \end{aligned}$$

The norm-squared of this projection is equal to

$$E(hu^T) \{E(uu^T)\}^{-1} E(uh^T)$$

since

$$\begin{aligned}\|a_0^\top \mu\|^2 &= E \left[E(hu^\top) \{E(uu^\top)\}^{-1} uu^\top \{E(uu^\top)\}^{-1} E(uh^\top) \right] \\ &= E(hu^\top) \{E(uu^\top)\}^{-1} E(uh^\top)\end{aligned}$$

2 The Geometry of Influence Functions

Problem setup: Z_1, \dots, Z_n are i.i.d random vectors with the density belongs to $\{p_Z(z; \theta), \theta \in \Omega\}$. $\theta = (\beta^\top, \eta^\top)^\top$, where $\beta^{q \times 1}$ is the parameter of interest and η is the nuisance parameter, may be finite- or infinite-dimensional. An estimator $\hat{\beta}_n$ of β is a q -dimensional measurable random function of Z_1, \dots, Z_n . Most reasonable estimators for β are *asymptotically linear*; that is, there exists a random vector (i.e., a q -dimensional measurable random function) $\varphi^{q \times 1}(Z)$ s.t. $E\{\varphi(Z)\} = 0^{q \times 1}$,

$$n^{1/2} (\hat{\beta}_n - \beta_0) = n^{-1/2} \sum_{i=1}^n \varphi(Z_i) + o_p(1).$$

It follows that by the CLT

$$n^{-1/2} \sum_{i=1}^n \varphi(Z_i) \xrightarrow{\mathcal{D}} N(0^{q \times 1}, E(\varphi\varphi^\top)),$$

and

$$n^{1/2} (\hat{\beta}_n - \beta_0) \xrightarrow{\mathcal{D}} N(0, E(\varphi\varphi^\top)).$$

Remark 1. The function $\varphi(Z)$ is defined with respect to the true distribution $p(z, \theta_0)$. Consequently, we sometimes may write $\varphi(Z, \theta)$. Therefore,

$$E_{\theta_0} \{\varphi(Z, \theta_0)\}$$

The class of influence functions for estimators belongs to the Hilbert space of all mean-zero q -dimensional random functions with finite variance.

Theorem 2.1. (Uniqueness of influence function)

An asymptotically linear estimator has a unique (a.s.) influence function.

Example 2. For $Z_i \sim N(\mu, \sigma^2)$, $i = 1, \dots, n$, $\hat{\mu}_n = n^{-1} \sum_{i=1}^n Z_i$, and $\hat{\sigma}_n^2 = n^{-1} \sum_{i=1}^n (Z_i - \hat{\mu}_n)^2$.

$$\begin{aligned}n^{1/2} (\hat{\mu}_n - \mu_0) &= n^{-1/2} \sum_{i=1}^n (Z_i - \mu_0) \\ n^{1/2} (\hat{\sigma}_n^2 - \sigma_0^2) &= n^{-1/2} \sum \left\{ (Z_i - \mu_0)^2 - \sigma_0^2 \right\} + n^{1/2} (\hat{\mu}_n - \mu_0)^2.\end{aligned}$$

Remark 2. (Asymptotically efficient)

We know that the variance of any unbiased estimator must be greater than or equal to the Cràmer-Rao lower bound; see, for example, Casella and Berger (2002, Section 7.3). When considering asymptotic theory, where we let the sample size n go to infinity, most reasonable estimators are asymptotically unbiased. Thus, we might expect the asymptotic variance of such asymptotically unbiased estimators also to be greater than the Cràmer-Rao lower bound. This indeed is the case for the most part, and estimators whose asymptotic variance equals the Cràmer-Rao lower bound are referred to as asymptotically efficient.

2.1 Super-Efficiency

Example 3. (Hodges's example)

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Definition 2.2. (Regular)

Consider a local data generating process (LDGP), where, for each n , the data are distributed according to θ_n , where $n^{1/2} (\theta_n - \theta^*) \rightarrow c$, for some $c \in R$. That is

$$Z_{1n}, Z_{2n}, \dots, Z_{nn} \sim_{\text{i.i.d}} p(z, \theta_n),$$

where $\theta_n = (\beta_n^\top, \eta_n^\top)^\top$, $\theta^* = (\beta^{*\top}, \eta^{*\top})^\top$. An estimator $\hat{\beta}_n(Z_{1n}, \dots, Z_{nn})$, is said to be regular if, for each θ^* , $n^{1/2} (\hat{\beta}_n - \beta_n)$ has a limiting distribution that does not depend on the LDGP.

Definition 2.3. (Score vector)

For $Z \sim p_Z(z, \theta)$, $\theta = (\beta^T, \eta^T)^T$,

$$S_\theta(z, \theta_0) = \left. \frac{\partial \log p_Z(z, \theta)}{\partial \theta} \right|_{\theta=\theta_0}$$

$$S_\theta(Z, \theta_0) = \{S_\beta^T(Z, \theta_0), S_\eta^T(Z, \theta_0)\}^T$$

where

$$S_\beta(z, \theta_0) = \left. \frac{\partial \log p_Z(z, \theta)}{\partial \beta} \right|_{\theta=\theta_0}^{q \times 1}$$

$$S_\eta(z, \theta_0) = \left. \frac{\partial \log p_Z(z, \theta)}{\partial \eta} \right|_{\theta=\theta_0}^{r \times 1}.$$

Theorem 2.4. Let the parameter of interest $\beta(\theta)$ be a q -dimensional function of the p -dimensional parameter θ , $q < p$, such that $\Gamma^{q \times p}(\theta) = \partial \beta(\theta) / \partial \theta^T$, the $q \times p$ -dimensional matrix of partial derivatives, exists, has rank q , and is continuous in θ in a neighborhood of the truth θ_0 . Also let $\hat{\beta}_n$ be an asymptotically linear estimator with influence function $\varphi(Z)$ such that $E_\theta(\varphi^T \varphi)$ exists and is continuous in θ in a neighborhood of θ_0 . Then if $\hat{\beta}_n$ is regular, this will imply that

$$E\{\varphi(Z) S_\theta^T(Z, \theta_0)\} = \Gamma(\theta_0).$$

In the special case where θ can be partitioned as $(\beta^T, \eta^T)^T$, we have

$$E\{\varphi(Z) S_\beta^T(Z, \theta_0)\} = I^{q \times q}$$

$$E\{\varphi(Z) S_\eta^T(Z, \theta_0)\} = 0^{q \times r},$$

where $I^{q \times q}$ is the $q \times q$ identity matrix and $0^{q \times r}$ is the $q \times r$ matrix of zeros.

2.2 Geometry of Influence Functions for Parametric Models

Consider the Hilbert space \mathcal{H} of all q -dimensional measurable functions of Z with mean zero and finite variance equipped with the inner product $\langle h_1, h_2 \rangle = E(h_1^T h_2)$.

Definition 2.5. (Tangent space)

We first note that the score vector $S_\theta(Z, \theta_0)$, under suitable regularity conditions, has mean zero ($E\{S_\theta(Z, \theta_0)\} = 0^{p \times 1}$). We can define the finite-dimensional linear subspace $\mathcal{T} \subset \mathcal{H}$ spanned by the p -dimensional score vector $S_\theta(Z, \theta_0)$ as the set of all q -dimensional mean-zero random vectors consisting of

$$B^{q \times p} S_\theta(Z, \theta_0), \quad \forall B^{q \times p}.$$

The linear subspace \mathcal{T} is referred to as the tangent space.

Definition 2.6. (Nuisance tangent space)

In the case where $\theta = (\beta^T, \eta^T)^T$, consider the linear subspace spanned by the nuisance score vector $S_\eta(Z, \theta_0)$,

$$B^{q \times r} S_\eta(Z, \theta_0), \quad \forall B^{q \times r}.$$

This space is referred to as the nuisance tangent space and will be denoted by Λ .

Note that Theorem 2.4 states that the q -dimensional influence function $\varphi_{\hat{\beta}_n}(Z)$ for $\hat{\beta}_n$ is orthogonal to the nuisance tangent space Λ .

2.3 Constructing Estimators

Influence functions of RAL estimators for β must satisfy conditions of Theorem 2.4, a natural question is whether the converse is true; that is, for any element of the Hilbert space satisfying conditions of Theorem 2.4, does there exist an RAL estimator for β with that influence function? Let $\varphi(Z)$ be a q -dimensional measurable function with zero mean and finite variance that satisfies conditions of Theorem 2.4. Define

$$m(Z, \beta, \eta) = \varphi(Z) - E_{\beta, \eta}\{\varphi(Z)\}.$$

Assume that we can find a **root- n consistent** estimator for the nuisance parameter $\hat{\eta}_n$ ($n^{1/2}(\hat{\eta}_n - \eta_0)$ is bounded in probability). In many cases the estimator $\hat{\eta}_n$ will be β -dependent ($\hat{\eta}_n(\beta)$). For example, we might use the MLE for η , or the restricted MLE for η , fixing the value of β . We argue that the solution to the equation

$$\sum_{i=1}^n m\{Z_i, \beta, \hat{\eta}_n(\beta)\} = 0$$

which we denote by $\hat{\beta}_n$ will be an asymptotically linear estimator with influence function $\varphi(Z)$.

Proof. By construction, we have

$$E_{\beta_0, \eta} \{m(Z, \beta_0, \eta)\} = 0,$$

or equivalently,

$$\int m(z, \beta_0, \eta) p(z, \beta_0, \eta) d\nu(z) = 0.$$

Consequently,

$$\begin{aligned} & \frac{\partial}{\partial \eta^T} \Big|_{\eta=\eta_0} \int m(z, \beta_0, \eta) p(z, \beta_0, \eta) d\nu(z) \\ &= \int \frac{\partial m(z, \beta_0, \eta_0)}{\partial \eta^T} p(z, \beta_0, \eta_0) d\nu(z) + \int m(z, \beta_0, \eta_0) S_\eta^T(z, \beta_0, \eta_0) p(z, \beta_0, \eta_0) d\nu(z) = 0. \end{aligned}$$

By definition, $E\{\varphi(Z)S_\eta^T(Z, \theta_0)\} = 0$. Consequently,

$$E\left\{\frac{\partial}{\partial \eta^T} m(Z, \beta_0, \eta_0)\right\} = 0.$$

Similarly, we can show that

$$E\left\{\frac{\partial}{\partial \beta^T} m(Z, \beta_0, \eta_0)\right\} = -I^{q \times q}.$$

A standard expansion yields,

$$\begin{aligned} 0 &= \sum_{i=1}^n m\{Z_i, \hat{\beta}_n, \hat{\eta}_n(\hat{\beta}_n)\} \\ &= \sum_{i=1}^n m\{Z_i, \beta_0, \hat{\eta}_n(\hat{\beta}_n)\} \\ &\quad + \left[\sum_{i=1}^n \frac{\partial m}{\partial \beta^T} \left\{ Z_i, \beta_n^*, \underbrace{\hat{\eta}_n(\hat{\beta}_n)}_{\text{Notice that this term is held fixed}} \right\} \right] (\hat{\beta}_n - \beta_0), \quad \beta_n^* \in (\hat{\beta}_n, \beta_0). \end{aligned}$$

Therefore,

$$\begin{aligned} & n^{1/2} (\hat{\beta}_n - \beta_0) \\ &= - \underbrace{\left[n^{-1} \sum_{i=1}^n \frac{\partial}{\partial \beta^T} m\{Z_i, \beta_n^*, \hat{\eta}_n(\hat{\beta}_n)\} \right]^{-1}}_{\downarrow} \left[n^{-1/2} \sum_{i=1}^n m\{Z_i, \beta_0, \hat{\eta}_n(\hat{\beta}_n)\} \right] \\ & \quad \left[E\left\{\frac{\partial}{\partial \beta^T} m(Z, \beta_0, \eta_0)\right\} \right]^{-1} = -I^{q \times q} \end{aligned}$$

For the second term,

$$\begin{aligned} & n^{-1/2} \sum_{i=1}^n m\{Z_i, \beta_0, \hat{\eta}_n(\hat{\beta}_n)\} \\ &= n^{-1/2} \sum_{i=1}^n m(Z_i, \beta_0, \eta_0) + \underbrace{\left\{ n^{-1} \sum_{i=1}^n \frac{\partial m(Z_i, \beta_0, \eta_n^*)}{\partial \eta^T} \right\}}_{\Rightarrow_p E\left\{\frac{\partial}{\partial \eta^T} m(Z, \beta_0, \eta_0)\right\}=0} \underbrace{\left[n^{1/2} \{ \hat{\eta}_n(\hat{\beta}_n) - \eta_0 \} \right]}_{\text{bounded in probability}}. \end{aligned}$$

Therefore,

$$\begin{aligned} n^{1/2} (\hat{\beta}_n - \beta_0) &= n^{-1/2} \sum_{i=1}^n m(Z_i, \beta_0, \eta_0) + o_p(1) \\ &= n^{-1/2} \sum_{i=1}^n \varphi(Z_i) + o_p(1) \end{aligned}$$

□